

### CHARACTERIZATION OF LOCAL AND REGIONAL UNCERTAINTY IN CASE OF MATURE HC RESERVOIRS

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# INTRODUCTION-I.

### Uncertainty ≠ Error

 Uncertainty expresses our incomplete knowledge

### Types of uncertainties:

- Local
- Regional
- Model

### Regionalized variable

- Multidimensional probability distribution
  - Random variable around a grid point or well location
    - There is a function which connects them

Uncertainty expresses our
 It can not be eliminated

- locations/grid nodes
  - Above a reservoir
- Used equation system

- Local uncertainty
  - Regional uncertainty

## INTRODUCTION-II.

## SEQUENTIAL SIMULATIONS

- For derivation local PDF's > Simulation of local
- For derivation many realizations of that random function which conects the local PDF's in the space
- Simulation of local uncertainty
- Simulation of regional uncertainty

## **KEY QUESTIONS:**

• How many realizations would be enough to get stable description of local uncertainties?

• Does this number depends on grid resolution? How?

## GOALS

- convergence of the multidimensional conditional distributions derived from increasing subset sizes of 100 realizations which are originated from sequential indicator simulation of well-averaged porosity data.
- how the local and regional uncertainty (Goovaerts, 2006) can be formulated by the terminology of variance components.
- how criterions for assessing the goodness of simulations given by Deutsch (1997), Goovaerts (1999, 2006) and Emery (2008) can be supplemented on the basis of the theory of variance decomposition.

an example for the process we suggest

The first two moments:

- Average/expected value
- Variance

#### Variance decomposition

- Within group variance (WGV)
- Between group variance (BGV)
- Convergences of WGV and BGV

Turbidity reservoir

## SEQUENCE OF MULTIDIMENSIONAL DISTRIBUTIONS

- Set containing I<sup>l</sup> stochastic realizations
  (l=1,2,...,L)
- Subsets from  $I^{\ell}$ :  $S_{\ell} := \bigcup I_{j}$ , where  $\ell = 1, ..., L$ 
  - l=1  $\longrightarrow$  N nodes l=2  $\longrightarrow$  2N nodes
    - $\ell = L$   $\longrightarrow$  LN nodes

 $S \Rightarrow S$ 

 for each *l S<sub>e</sub>* is a realization of the multidimensional distribution generated by the algorithm

# SEQUENCE OF THE GRID AVERAGES

•  $E_{\ell}^{g}$  an average value calculated for  $S^{\ell}$   $(S^{\ell} := \bigcup_{j=1}^{\ell} I_{j}, \ell = 1, ..., L)$ under g grid resolution.

•  $SE_{\ell}^{g} := \frac{1}{\ell \cdot N} \sum_{j=1}^{\ell \cdot N} z^{(i)}(u_{j}), \ \ell = 1, 2, ..., a$  sequence of averages for increasing  $\ell$ 

•  $SE_1^g := \{average \ from \ N \ nodes\}$  $SE_2^g := \{average \ from 2N \ nodes\}$ 

 $SE_L^g := \{average from LN nodes\}$ 

•  $\lim_{\ell \to \infty} SE^{g}_{\ell} = E^{g}$  according to the strong law of large numbers

# ABOUT THE CONVERGENCE OF GRID AVERAGES $\lim_{\ell \to \infty} SE_{\ell}^{g} = E^{g}$

Valid only for the underlying g grid geometry since

- stationary is the property of the multivariate random function and not that of the underlying geological process;
- this random function may change with the change of scale.
- It is conditioned to
  - the original data set
  - spatial configuration.
- A kind of `conditional convergence'.

## VARIANCE DECOMPOSITION-I

There are L stochastic images above N grid nodes

One-way ANOVA: there is a set of LN values which are nested within N nodes



## VARIANCE DECOMPOSITION-III Within-group and between-group variances



#### **AROUND THE GRID AVERAGE**

It measures variance of the node-averages (group averages) around the grid average (main-average).



#### AROUND THE GRID-NODE AVERAGES

It measures how individual values (simulated node values) deviate from their particular node average (group average).



## **INTERPRETATION OF WGV**





It measures how individual values deviate from the group average in the whole sample.

The smaller the WGV the more stable the estimations can be derived at grid nodes , in average.

This component measures the average stability of our estimation at grid nodes in the *l* realizations.

**Its convergence** means that the estimation stability approaches such a value which can not be decreased so far within the simulation method and the *g* grid resolution. The limit is the **accesible maximum estimation stability** 

## **INTERPRETATION OF BGV**

VERA



It measures variance of the group averages (node averages) around the main average (grid-average).

Node averages show a direct relation to the underlying geological process

The more heterogeneous this geological background the larger the variance being measured between node averages.

It can reflect the degree of lateral heterogeneity of that geological process which is transformed to the grid.

In the limit, the E-type grid shows that lateral heterogeneity which will not change so far under the used simulations algorithm and grid resolution.

The limit of the sequence of between-group variances is exactly that variance which in this situation measures the variability between grid nodes.

## **RELATIONS BETWEEN WGV AND BGV-I**

#### If (WGV < BGV) and $(l < \infty)$

- Under the given { realizations, the heterogeneity of the geological process is higher than the average estimation stability obtained at grid nodes
- Under the given grid resolution, the total variance of the E-type grid can rather be drawn back to the underlying geology than the instability of the estimation method applied.
- The pooled *t* realizations on the given grid resolution can be accepted, because it reflects mostly the underlying geology
- Since l is finite, there is a possibility for changing this relation if the number realization is increased.

#### If (WGV < BGV) in the limit

- there is no way for changing this relation without altering either the simulation algorithm or the grid resolution.
- in general the actual grid resolution and simulation algorithm are adequate to the given problem. At least in the sense that if *l* is large enough, the E-type estimation of the pooled realizations will be affected mainly by the geological situation and not the instability of the node-estimation processes.

## **RELATIONS BETWEEN WGV AND BGV-II**

#### If (WGV > BGV) and $(l < \infty)$

- under the given *l* realizations the revealed lateral heterogeneity of the underlying geological process is smaller than the average estimation stability obtained at grid nodes.
- under the given grid resolution, the total variance of the E-type grid is mainly controlled by the instability of estimation method applied.
- the pooled *l* realizations on the given grid resolution cannot be accepted, because it does not reflect the geology.
- since l is finite, there is a possibility for changing this relation if the number realizations is increased.

#### If (WGV > BGV) in the limit

- there is no way for changing this relation without altering either the simulation algorithm or the grid resolution.
- in general the actual grid resolution and simulation algorithm are not adequate to the given problem. At least in the sense that if *l* is large enough, the E-type estimation of the pooled realizations will be affected mainly by instability of the local estimations.

## **APPROXIMATION OF THE LIMIT**

the limit must be existing;  $\longrightarrow$   $\square$  Unquestionably 

the "tendency" of the **Rather 'hope'**... members of sequences can be evaluated from the finite number of members

The analytical form of the sequences can be approximated by a bounded, monoton, non-linear regression, if its domain is restricted to the set of integer numbers

If  $l_{min}$  be that particular serial number from which this approximation can be done, then

since the convergence does not depend on omitting finite number of members,

**<u>L</u>**min gives the minimum number of realizations which is <u>necessary but</u> not sufficient for assessing the regional uncertainty.

## CONVERGENCE OF WITHIN GROUP VARIANCES (average estimation stability)



### CONVERGENCE OF BETWEEN GROUP VARIANCES (revealed average geological heterogeneity)



# CRITERIA FOR 'GOOD' AND 'WRONG' ESTIMATIONS



## CONSEQUENCE

- "How many realizations are enough for reaching a 'good' spatial average?"
  - Note: "if the limit has to be approached within a particular (ε<sub>0</sub>) deviation"
  - this question can be drawn back to the Heine's definition of convergence

 $\left|\overline{SE^{g}_{\ell} - E^{g}}\right| < \varepsilon_{0}, \ \left(\ell_{0} < \ell\right)$ 

$$\left(SE^{g}_{\ell} - \mathcal{E}_{0}\right) < E^{g} < \left(SE^{g}_{\ell} + \mathcal{E}_{0}\right) \quad if \ \ell_{0} < \ell_{0}$$

the infinum of the set of  $\{\ell | \ell > \ell_0\}$  is the requested solution.

## SUMMARY

### Relations

- Another criterion for assessing the goodness of simulation

$$WGV^{g}_{\ell} \underset{\ell \to \infty}{\Rightarrow} WGV^{g} < BGV^{g}_{\ell} \underset{\ell \to \infty}{\Rightarrow} BGV^{g}$$

Criterion for the necessary and sufficient number of realizations

 $\left| SE_{\ell}^{g} - E^{g} \right| < \varepsilon_{0}, \ \left( \ell_{0} < \ell \right)$ 

 $\left(SE_{\ell}^{g} - \varepsilon_{0}\right) < E^{g} < \left(SE_{\ell}^{g} + \varepsilon_{0}\right) \quad if \ \ell_{0} < \ell$ 

# MANY THANKS FOR YOUR ATTENTION

